General Description

The MAX5432–MAX5435 nonvolatile, linear-taper, digital potentiometers perform the function of a mechanical potentiometer, but replace the mechanics with a simple 2-wire serial interface. Each device performs the same function as a discrete potentiometer or a variable resistor and has 32 tap points.

The MAX5432–MAX5435 feature an internal, nonvolatile, electrically erasable programmable read-only memory (EEPROM) that returns the wiper to its previously stored position at power-up. The fast-mode l²C[†]-compatible serial interface allows communication at data rates up to 400kbps, minimizing board space and reducing interconnection complexity. Each device is available with one of four factory-preset l²C addresses (see the *Selector Guide*).

Use the MAX5432–MAX5435 in applications requiring digitally controlled resistors. Two resistance values are available ($50k\Omega$ and $100k\Omega$) in a voltage-divider or variable resistor configuration. The nominal resistor temperature coefficient is $35ppm/^{\circ}C$ end-to-end, and only $5ppm/^{\circ}C$ ratiometric, making the devices ideal for applications requiring a low-temperature-coefficient variable resistor such as low-drift, programmable-gain amplifier circuit configurations.

The MAX5432/MAX5433 are available in a 3mm x 3mm 8pin TDFN package and the MAX5434/MAX5435 are available in a 6-pin thin SOT23 package. The MAX5432– MAX5435 are specified over the extended (-40°C to +85°C) temperature range.

Applications

Mechanical Potentiometer Replacement

Low-Drift Programmable-Gain Amplifiers

Volume Control

Liquid-Crystal Display (LCD) Screen Adjustment

Selector Guide appears at end of data sheet.

[†]Purchase of I²C components from Maxim Integrated Products, Inc., or one of its sublicensed Associated Companies, conveys a license under the Philips I²C Patent Rights to use these components in an I²C system, provided that the system conforms to the I²C Standard Specification as defined by Philips.

_Features

- Tiny 3mm x 3mm 8-Pin TDFN and 6-Pin Thin SOT23 Packages
- Power-On Recall of Wiper Position from Nonvolatile Memory
- 35ppm/°C End-to-End Resistance Temperature Coefficient
- ♦ 5ppm/°C Ratiometric Temperature Coefficient
- 50kΩ/100kΩ Resistor Values
- ♦ Fast 400kbps I²C-Compatible Serial Interface
- ♦ 500nA (typ) Static Supply Current
- ♦ +2.7V to +5.25V Single-Supply Operation
- 32 Tap Positions
- ±0.15 LSB INL (typ), ±0.15 LSB DNL (typ)

_Ordering Information

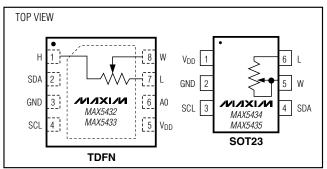
PART	TEMP RANGE	PIN-PACKAGE
MAX5432LETA	-40°C to +85°C	8 TDFN-EP**
MAX5432META*	-40°C to +85°C	8 TDFN-EP**
MAX5433LETA	-40°C to +85°C	8 TDFN-EP**
MAX5433META*	-40°C to +85°C	8 TDFN-EP**
MAX5434LEZT-T	-40°C to +85°C	6 Thin SOT23-6
MAX5434MEZT-T*	-40°C to +85°C	6 Thin SOT23-6
MAX5434NEZT-T*	-40°C to +85°C	6 Thin SOT23-6
MAX5434PEZT-T*	-40°C to +85°C	6 Thin SOT23-6
MAX5435LEZT-T	-40°C to +85°C	6 Thin SOT23-6
MAX5435MEZT-T*	-40°C to +85°C	6 Thin SOT23-6
MAX5435NEZT-T*	-40°C to +85°C	6 Thin SOT23-6
MAX5435PEZT-T*	-40°C to +85°C	6 Thin SOT23-6

*Future product—contact factory for availability. **EP = Exposed pad.

EF = Exposed part

Pin Configurations

Maxim Integrated Products 1



For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

ABSOLUTE MAXIMUM RATINGS

V _{DD} to GND	0.3V to +6.0V
SDA, SCL to GND	0.3V to +6.0V
A0, H, L, and W to GND	0.3V to (V _{DD} + 0.3V)
Maximum Continuous Current into H, L,	and W
MAX5432/MAX5434	±1.3mA
MAX5433/MAX5435	±0.6mA
Input/Output Latchup Immunity	±50mA

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(V_{DD} = +2.7V \text{ to } +5.25V, V_H = V_{DD}, V_L = GND, T_A = -40^{\circ}C \text{ to } +85^{\circ}C, \text{ unless otherwise noted. Typical values are at } V_{DD} = +5V, T_A = +25^{\circ}C.)$ (Note 1)

PARAMETER	SYMBOL	CONDITIONS		MIN	ТҮР	MAX	UNITS
DC PERFORMANCE		·					
Resolution				32			Taps
End-to-End Resistance	Dere	MAX5432/MAX5434		37.5	50	62.5	kΩ
End-lo-End nesistance	R _{H-L}	MAX5433/MAX5435		75	100	125	K52
End-to-End Resistance Temperature Coefficient	TCR				35		ppm/°C
Ratiometric Resistance Temperature Coefficient					5		ppm/°C
		Variable register (Nate 0)	$V_{DD} = 5V$		±0.15	±0.5	
1. INI 11 11		Variable resistor (Note 2)	$V_{DD} = 3V$		±0.15	±0.5	
Integral Nonlinearity	INL	Voltage-divider,	$V_{DD} = 5V$		±0.15	±0.5	LSB
		MAX5432/MAX5433 (Note 3)	$V_{DD} = 3V$		±0.15	±0.5	
			$V_{DD} = 5V$		±0.15	±0.5	Ì
		Variable resistor (Note 2)	$V_{DD} = 3V$		±0.15	±0.5	
Differential Nonlinearity	DNL	Voltage-divider,	$V_{DD} = 5V$		±0.15	±0.5	LSB
		MAX5432/MAX5433 (Note 3)	$V_{DD} = 3V$		±0.15	±0.5	
		MAX5432, 50kΩ	•			-0.5	1.00
Full-Scale Error (Note 4)		MAX5433, 100kΩ				-0.5	LSB
Zara Casla Error (Nata E)		MAX5432, 50k Ω				+0.5	
Zero-Scale Error (Note 5)		MAX5433, 100kΩ				+0.5	LSB
Wiper Resistance	Rw	MAX5432/MAX5433 (Note 6)			610	1200	Ω
DIGITAL INPUTS							
Input High Voltage	VIH	(Note 7)		0.7 x V _{DD}			V
Input Low Voltage	VIL	(Note 7)				0.3 x V _{DD}	V
Input Leakage Current	ILEAK					±1	μA
Input Capacitance					5		рF

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = +2.7V \text{ to } +5.25V, V_{H} = V_{DD}, V_{L} = GND, T_{A} = -40^{\circ}C \text{ to } +85^{\circ}C, \text{ unless otherwise noted. Typical values are at } V_{DD} = +5V, T_{A} = +25^{\circ}C.) \text{ (Note 1)}$

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	МАХ	UNITS
DYNAMIC CHARACTERISTICS						
-3dB Bandwidth (Note 8)		MAX5432/MAX5434		500		kHz
		MAX5433/MAX5435		250		KIIZ
Wiper Settling Time (Note 9)		MAX5432/MAX5434		0.5		110
wiper Settling Time (Note 9)		MAX5433/MAX5435		1.0		μs
NONVOLATILE MEMORY RELIAE	BILITY					
Data Retention		$T_A = +85^{\circ}C$		50		Years
Endurance		$T_A = +25^{\circ}C$		200,000		Stores
		$T_A = +85^{\circ}C$		50,000		Siores
POWER SUPPLY						
Power-Supply Voltage	V _{DD}		2.70		5.25	V
Standby Current	IDD	Digital inputs = V_{DD} or GND, $T_A = +25^{\circ}C$		0.5	2	μA
Programming Current		During nonvolatile write; digital inputs = V _{DD} or GND (Note 10)		200	900	μA

TIMING CHARACTERISTICS

 $(V_{DD} = +2.7V \text{ to } +5.25V, V_H = V_{DD}, V_L = GND, T_A = -40^{\circ}C \text{ to } +85^{\circ}C, \text{ unless otherwise noted. Typical values are at } V_{DD} = +5V, T_A = +25^{\circ}C.)$ (Figures 1 and 2) (Note 11)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS
SCL Clock Frequency	fscl				400	kHz
Setup Time for START Condition	tsu-sta		0.6			μs
Hold Time for START Condition	thd-sta		0.6			μs
CLK High Time	thigh		0.6			μs
CLK Low Time	tLOW		1.3			μs
Data Setup Time	tsu-dat		100			ns
Data Hold Time	thd-dat		0		0.9	μs
SDA, SCL Rise Time	t _R				300	ns
SDA, SCL Fall Time	tF				300	ns
Setup Time for STOP Condition	tsu-sto		0.6			μs
Bus Free Time Between STOP and START Condition	^t BUF		1.3			μs
Pulse Width of Spike Suppressed	tsp			50		ns
Capacitive Load for Each Bus Line	CB	(Note 12)		400		pF
Nonvolatile Store Time		Idle time required after a nonvolatile memory write (Note 13)			12	ms

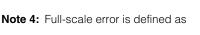
Note 1: All devices are production tested at $T_A = +25^{\circ}C$ and are guaranteed by design and characterization for $-40^{\circ}C < T_A < +85^{\circ}C$.



TIMING CHARACTERISTICS (continued)

 $(V_{DD} = +2.7V \text{ to } +5.25V, V_H = V_{DD}, V_L = GND, T_A = -40^{\circ}C \text{ to } +85^{\circ}C, \text{ unless otherwise noted. Typical values are at } V_{DD} = +5V, T_A = +25^{\circ}C.)$ (Figures 1 and 2) (Note 1)

- **Note 2:** The DNL and INL are measured with the potentiometer configured as a variable resistor. For the 3-terminal potentiometers (MAX5432/MAX5433), H is unconnected and L = GND. At V_{DD} = 5V, W is driven with a source current of 80µA for the 50k Ω configuration, and 40µA for the 100k Ω configuration. At V_{DD} = 3V, W is driven with a source current of 40µA for the 50k Ω configuration, and 20µA for the 100k Ω configuration.
- **Note 3:** The DNL and INL are measured with the potentiometer configured as a voltage-divider with H = V_{DD} and L = GND (MAX5432/MAX5433 only). The wiper terminal is unloaded and measured with an ideal voltmeter.



Note 5: Zero-scale error is defined as

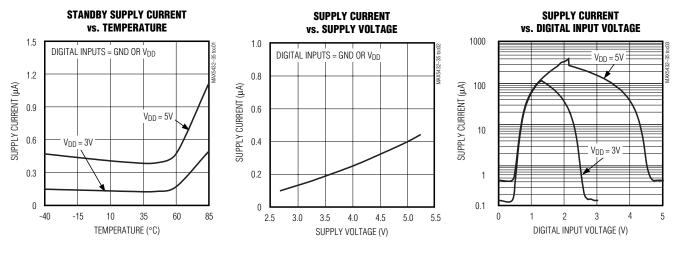


V_W - V_H

- Note 6: The wiper resistance is the worst value measured by injecting the currents given in Note 2 into W with L = GND. $R_W = (V_W - V_H) / I_W.$
- Note 7: The device draws current in excess of the specified supply current when the digital inputs are driven with voltages between (V_{DD} 0.5V) and (GND + 0.5V). See the Supply Current vs. Digital Input Voltage graph in the *Typical Operating Characteristics*.
- **Note 8:** Wiper is at midscale with a 10pF capacitive load. Potentiometer set to midscale, L = GND, an AC source is applied to H, and the output is measured as 3dB lower than the DC W/H value in dB.
- **Note 9:** This is measured from the STOP pulse to the time it takes the output to reach 50% of the output step size (divider mode). It is measured with a maximum external capacitive load of 10pF.
- Note 10: The programming current exists only during NV writes (12ms typ).
- Note 11: Digital timing is guaranteed by design and characterization, and is not production tested.
- Note 12: An appropriate bus pullup resistance must be selected depending on board capacitance. Refer to the I²C-bus specification document linked to this web address: www.semiconductors.philips.com/acrobat/literature/9398/39340011.pdf
- Note 13: The idle time begins from the initiation of the stop pulse.

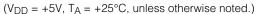
($V_{DD} = +5V$, $T_A = +25^{\circ}C$, unless otherwise noted.)

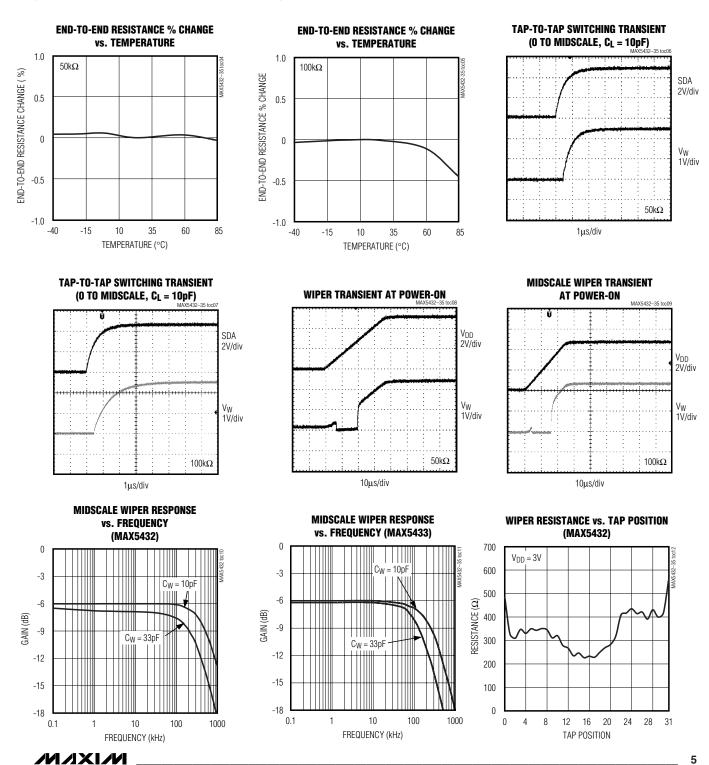


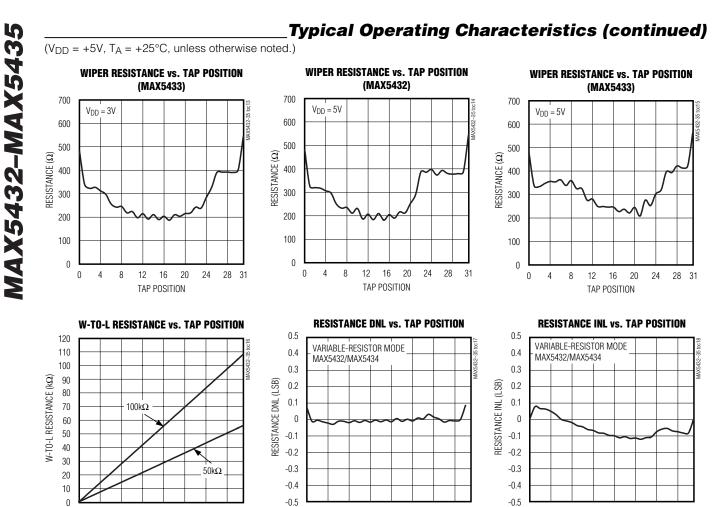












28 31

TAP POSITION

0 4 8 12 16 20 24

28 31

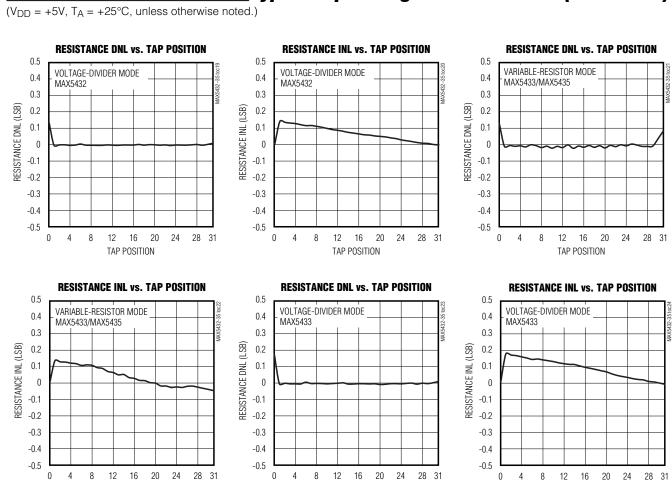
TAP POSITION

0 4 8 12 16 20 24

28 31

TAP POSITION

0 4 8 12 16 20 24



TAP POSITION

Typical Operating Characteristics (continued)

TAP POSITION

TAP POSITION

_Pin Description

	PIN							
TDFN	THIN SOT23	NAME	FUNCTION					
1	_	Н	High Terminal					
2	4	SDA	I ² C-Compatible Interface Data Input					
3	2	GND	Ground					
4	3	SCL	I ² C-Compatible Interface Clock Input					
5	1	V _{DD}	Power-Supply Input. Bypass with a 0.1µF capacitor from V _{DD} to GND.					
6	_	A0	Address Input. Sets the I ² C address. Connect to V _{DD} or GND. Do not leave A0 floating.					
7	6	L	Low Terminal					
8	5	W	Wiper Terminal					
EP	_	EP	Exposed Pad. Internally connected to GND.					

Detailed Description

The MAX5432–MAX5435 contain a resistor array with 31 resistive elements. The MAX5432/MAX5434 provide a total end-to-end resistance of 50k Ω , and the MAX5433/MAX5435 provide an end-to-end resistance of 100k Ω .

The MAX5432/MAX5433 allow access to the high, low, and wiper terminals for a standard voltage-divider configuration. Connect H, L, and W in any desired configuration as long as their voltages fall between GND and V_{DD}. The MAX5434/MAX5435 are variable resistors with H internally connected to the wiper.

A simple 2-wire I²C-compatible serial interface moves the wiper among the 32 tap points. Eight data bits, an address byte, and a control byte program the wiper position. A nonvolatile memory stores and recalls the wiper position in the nonvolatile memory upon power-up. The nonvolatile memory is guaranteed for 200,000 wiper store cycles and 50 years for wiper data retention.

Digital Interface

The MAX5432–MAX5435 feature an internal, nonvolatile EEPROM that returns the wiper to its previously stored position at power-up. The shift register decodes the control and address bits, routing the data to the proper memory registers. Write data to the volatile memory register to immediately update the wiper position, or write data to the nonvolatile register for storage. Writing to the nonvolatile register takes a minimum of 12ms.

The volatile register retains data as long as the device is enabled and powered. Removing power clears the volatile register. The nonvolatile register retains data even after power is removed. Upon power-up, the power-on reset circuitry and internal oscillator control the transfer of data from the nonvolatile register to the volatile register.

Serial Addressing

1AX5432-MAX5435

The MAX5432–MAX5435 operate as a slave that sends and receives data through an I²C- and SMBus[™]-compatible 2-wire interface. The interface uses a serial data access (SDA) line and a serial clock line (SCL) to achieve bidirectional communication between master(s) and slave(s). A master, typically a microcontroller, initiates all data transfers to and from the MAX5432–MAX5435, and generates the SCL clock that synchronizes the data transfer (Figure 1).

SDA operates as both an input and an open-drain output. SDA requires a pullup resistor, typically $4.7k\Omega$. SCL only operates as an input. SCL requires a pullup resistor ($4.7k\Omega$ typ) if there are multiple masters on the 2-wire interface, or if the master in a single-master system has an open-drain SCL output.

Each transmission consists of a START (S) condition (Figure 3) sent by a master, followed by the MAX5432–MAX5435 7-bit slave address plus the 8th bit (Figure 4), 1 command byte (Figure 7) and 1 data byte, and finally a STOP (P) condition (Figure 3).

Start and Stop Conditions

Both SCL and SDA remain high when the interface is not busy. A master signals the beginning of a transmission with a START (S) condition by transitioning SDA from high to low while SCL is high. When the master has finished communicating with the slave, it issues a STOP (P) condition by transitioning the SDA from low to

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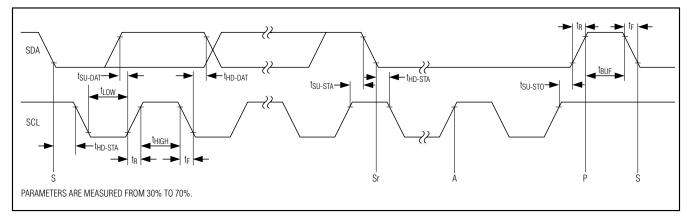


Figure 1. I²C Serial-Interface Timing Diagram

high while SCL is high. The bus is then free for another transmission (Figure 3).

Bit Transfer

One data bit is transferred during each clock pulse. The data on the SDA line must remain stable while SCL is high (Figure 5).

Acknowledge The acknowledge bit is a clocked 9th bit that the recipient uses to handshake receipt of each byte of data (Figure 6). Each byte transferred effectively requires 9 bits. The master generates the 9th clock pulse, and the recipient pulls down SDA during the acknowledge clock pulse, so the SDA line is stable low during the high period of the clock pulse. When the master transmits to the MAX5432–MAX5435, the devices generate the acknowledge bit because the MAX5432–MAX5435 are the recipients.

Slave Address

The MAX5432–MAX5435 have a 7-bit-long slave address (Figure 4). The 8th bit following the 7-bit slave address is the NOP/W bit. Set the NOP/W bit low for a write command and high for a no-operation command.

Table 1a shows four possible slave addresses for the MAX5432/MAX5433 and Table 1b shows four possible slave addresses for the MAX5434/MAX5435. The first 4 bits (MSBs) of the slave addresses are always 0101. Bits A2 and A1 are factory programmed for the MAX5432/MAX5433 (Table 1a). Connect the A0 input (MAX5432/MAX5433 only) to either GND or V_{DD} to select one of two I²C device addresses. Each device must have a unique address to share the bus. A maximum of four MAX5432/MAX5433 devices can share the same bus. Bits A2, A1, and A0 are factory programmed for the MAX5434/MAX5435 (Table 1b).



Table 1a. Address Codes(MAX5432/MAX5433 Only)

DADT	ADDRESS BYTE												
PART SUFFIX	A 6	A5	A 4	A 3	A2	A 1	A 0	NOP/W					
L	0	1	0	1	0	0	0	NOP/W					
L	0	1	0	1	0	0	1	NOP/W					
М	0	1	0	1	1	0	0	NOP/W					
М	0	1	0	1	1	0	1	NOP/W					

Table 1b. Address Codes (MAX5434/MAX5435 Only)

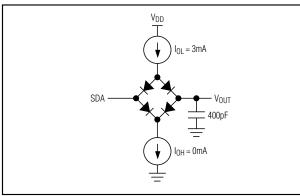
DADT	ADDRESS BYTE												
PART SUFFIX	A6	A5	A 4	A3	A2	A1	A0	NOP/W					
L	0	1	0	1	0	0	0	NOP/W					
м	0	1	0	1	1	0	0	NOP/W					
N	0	1	0	1	0	1	0	NOP/W					
Р	0	1	0	1	1	1	0	NOP/W					

Message Format for Writing

A write to the MAX5432–MAX5435 consists of the transmission of the device's slave address with the 8th bit set to zero, followed by at least 1 byte of information. The 1st byte of information is the command byte. The bytes received after the command byte are the data bytes. The 1st data byte goes into the internal register of the MAX5432–MAX5435 as selected by the command byte (Figure 8).

MAX5432-MAX5435





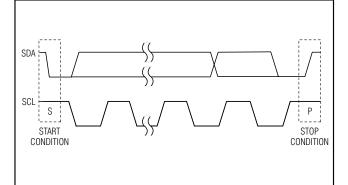
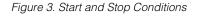


Figure 2. Load Circuit



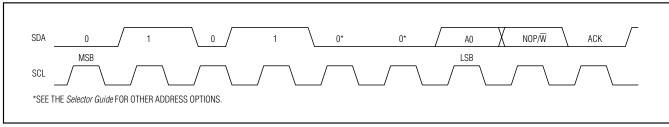


Figure 4. Slave Address

Command Byte

Use the command byte to select the destination of the wiper data (nonvolatile or volatile memory registers) and swap data between nonvolatile and volatile memory registers (see Table 2).

Data Byte The MAX5432–MAX5435 use the first 5 bits (MSBs, D7–D3) of the data byte to set the position of the wiper. The last 3 bits (D2, D1, and D0) are don't care bits (see Table 2).

Command Descriptions

VREG: The data byte writes to the volatile memory register and the wiper position updates with the data in the volatile memory register.

NVREG: The data byte writes to the nonvolatile memory register. The wiper position is unchanged.

NVREGxVREG: Data transfers from the nonvolatile memory register to the volatile memory register (wiper position updates).

VREGxNVREG: Data transfers from the volatile memory register into the nonvolatile memory register.

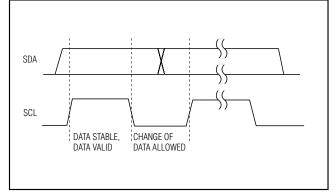
REGISTER				AD	DRE	SS B	YTE					COMMAND BTYE						D	ΑΤΑ	BYT	Έ								
		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	
SCL CYCLE NUMBER	START	A6	A5	A4	A3	A2	A1	A0	N O P∕ ₩	A C K	C7	C6	C5	C4	C3	C2	C1	CO	A C K	D7	D6	D5	D4	D3	D2	D1	D0	A C K	STOP
VREG		0	1	0	1	A2	A1	A0	0		0	0	0	1	0	0	0	1		D7	D6	D5	D4	D3	Х	Х	Х		
NVREG		0	1	0	1	A2	A1	A0	0		0	0	1	0	0	0	0	1		D7	D6	D5	D4	D3	Х	Х	Х		
NVREGxVREG		0	1	0	1	A2	A1	A0	0		0	1	1	0	0	0	0	1		D7	D6	D5	D4	D3	Х	Х	Х		
VREG×NVREG		0	1	0	1	A2	A1	A0	0		0	1	0	1	0	0	0	1		D7	D6	D5	D4	D3	Х	Х	Х		

Table 2. Command Byte Summary

X = Don't care.







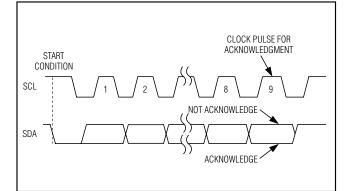


Figure 5. Bit Transfer

Figure 6. Acknowledge

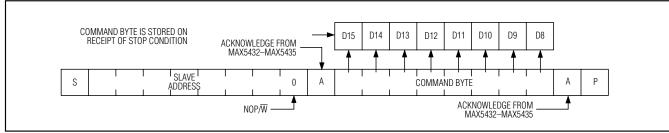


Figure 7. Command Byte Received

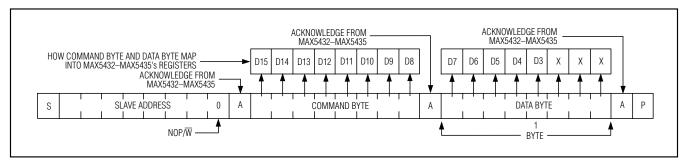


Figure 8. Command and Single Data Byte Received

Nonvolatile Memory

The internal EEPROM consists of a 5-bit nonvolatile register that retains the value written to it before the device is powered down. The nonvolatile register is programmed with the zeros at the factory. Wait a minimum of 12ms after writing to NVREG before sending another command.

Power-Up

Upon power-up, the MAX5432–MAX5435 load the data stored in the nonvolatile memory register into the volatile memory register, updating the wiper position

with the data stored in the nonvolatile memory register. This initialization period takes 20µs.

Standby

The MAX5432–MAX5435 feature a low-power standby mode. When the device is not being programmed, it goes into standby mode and current consumption is typically 0.5μ A.



МІЛХІЛ МАХ5432-МАХ5435

32-Tap, Nonvolatile, I²C, Linear, Digital

VOUT

Figure 9. Positive LCD Bias Control Using a Voltage-Divider

Potentiometers

MAX5432 MAX5433 lн

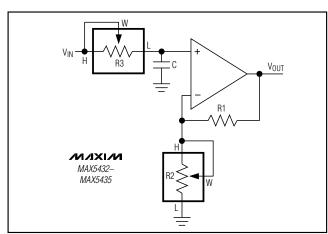


Figure 11. Programmable Filter

Applications Information

Use the MAX5432–MAX5435 in applications requiring digitally controlled adjustable resistance, such as LCD contrast control (where voltage biasing adjusts the display contrast), or for programmable filters with adjustable gain and/or cutoff frequency.

Positive LCD Bias Control

Figures 9 and 10 show an application where the voltage-divider or variable resistor is used to make an adjustable, positive LCD bias voltage. The op-amp provides buffering and gain to the resistor-divider network made by the potentiometer (Figure 9) or to a fixed resistor and a variable resistor (Figure 10).

Programmable Filter

Figure 11 shows the configuration for a 1st-order programmable filter. The gain of the filter is adjusted by

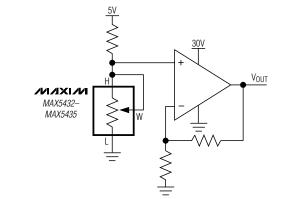


Figure 10. Positive LCD Bias Control Using a Variable Resistor

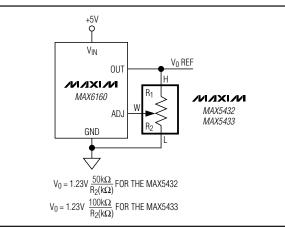


Figure 12. Adjustable Voltage Reference

R2, and the cutoff frequency is adjusted by R3. Use the following equations to calculate the gain (G) and the 3dB cutoff frequency (f_C).

$$G = 1 + \frac{R1}{R2}$$
$$f_{C} = \frac{1}{2\pi \times R3 \times C}$$

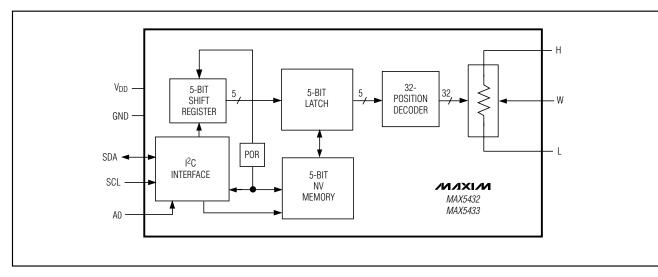
Adjustable Voltage Reference

Figure 12 shows the MAX5432/MAX5433 used as the feedback resistors in an adjustable voltage reference application. Independently adjust the output voltages of the MAX6160 from 1.23V to (V_{IN} - 0.2V) by changing the wiper position of the MAX5432/MAX5433.

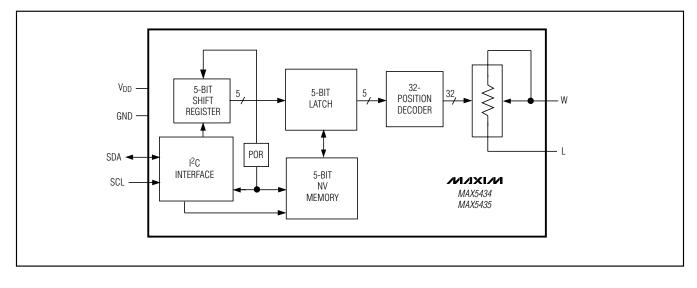




MAX5432/MAX5433 Functional Diagram



_MAX5434/MAX5435 Functional Diagram



		_Selector	Guiue
PART	TOP MARK	I ² C ADDRESS	R (k Ω)
MAX5432LETA	ANG	010100A ₀	50
MAX5432META	ANI	010110A ₀	50
MAX5433LETA	ANF	010100A ₀	100
MAX5433META	ANH	010110A ₀	100
MAX5434LEZT	AABX	0101000	50
MAX5434MEZT	AABY	0101100	50
MAX5434NEZT	AABS	0101010	50
MAX5434PEZT	AABU	0101110	50
MAX5435LEZT	AABW	0101000	100
MAX5435MEZT	AABV	0101100	100
MAX5435NEZT	AABZ	0101010	100
MAX5435PEZT	AABT	0101110	100

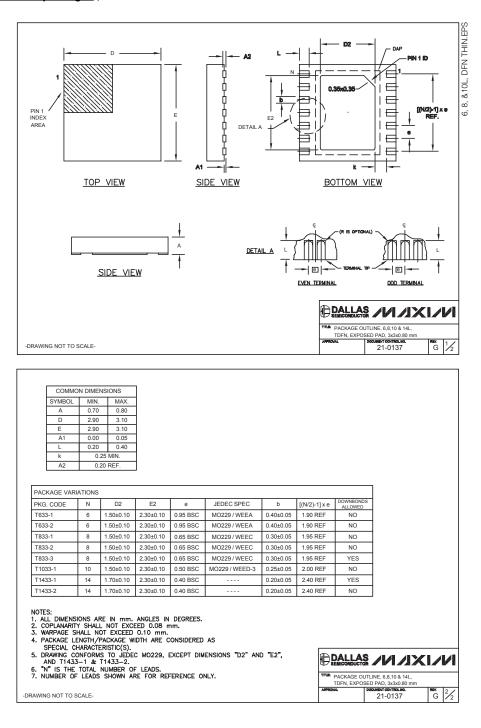
Selector Guide

TRANSISTOR COUNT: 7817 PROCESS: BICMOS

Chip Information

Package Information

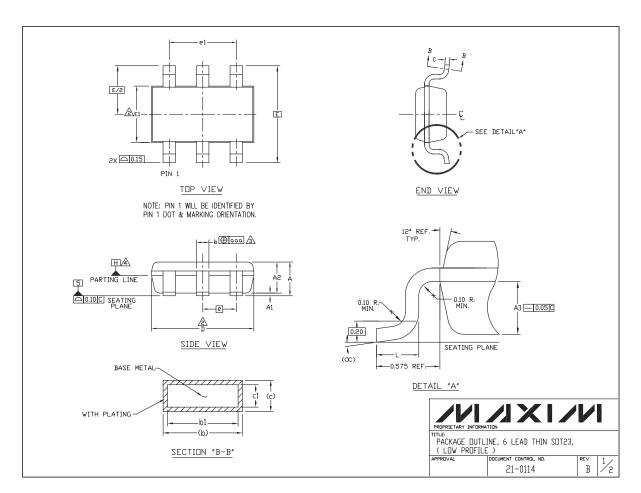
(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to <u>www.maxim-ic.com/packages</u>.)





_Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)



Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to <u>www.maxim-ic.com/packages</u>.)

NOTES:

- 1. ALL DIMENSIONS ARE IN MILLIMETERS.
- ✓ "D" AND "E1" ARE REFERENCE DATUM AND DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS, AND ARE MEASURED AT THE BOTTOM PARTING LINE. MOLD FLASH OR PROTRUSION SHALL NOT EXCEED 0.15mm ON "D" AND 0.25mm ON "E" PER SIDE.
- THE LEAD WIDTH DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.07mm TOTAL IN EXCESS OF THE LEAD WIDTH DIMENSION AT MAXIMUM MATERIAL CONDITION.
- A DATUM PLANE "H" LOCATED AT MOLD PARTING LINE AND COINCIDENT WITH LEAD, WHERE LEAD EXITS PLASTIC BODY AT THE BOTTOM OF PARTING LINE.
- THE LEAD TIPS MUST LINE WITHIN A SPECIFIED TOLERANCE ZONE. THIS TOLERANCE ZONE IS DEFINED BY TWO PARALLEL LINES. ONE PLANE IS THE SEATING PLANE, DATUM [-C-]; AND THE OTHER PLANE IS AT THE SPECIFIED DISTANCE FROM [-C-] IN THE DIRECTION INDICATED. FORMED LEADS SHALL BE PLANAR WITH RESPECT TO ONE ANOTHER WITH 0.10mm AT SEATING PLANE.
- THIS PART IS COMPLIANT WITH JEDEC SPECIFICATION MO-193 EXCEPT FOR THE "e" DIMENSION WHICH IS 0.95mm INSTEAD OF 1.00mm. THIS PART IS IN FULL COMPLIANCE TO EIAJ SPECIFICATION SC-74.

	SYM	BOLS								
	MIN	NDM	MAX							
A	-	-	1.10							
A1	0.05	0.075	0.10							
A2	0.85	0.88	0.90							
A3	0.50 BSC									
b	0.30	-	0.45							
b1	0.25	0.35	0.40							
С	0.15	-	0.20							
⊂1	0.12	0.127	0.15							
D	2.80	2.90	3.00							
E		2.75 BSC								
E1	1.55	1.60	1.65							
L	0.30	0.40	0.50							
e1		1.90 BSC								
e		0.95 BSC								
20	0- 4- 8-									
ممم		0.20								



MAX5432-MAX543;

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